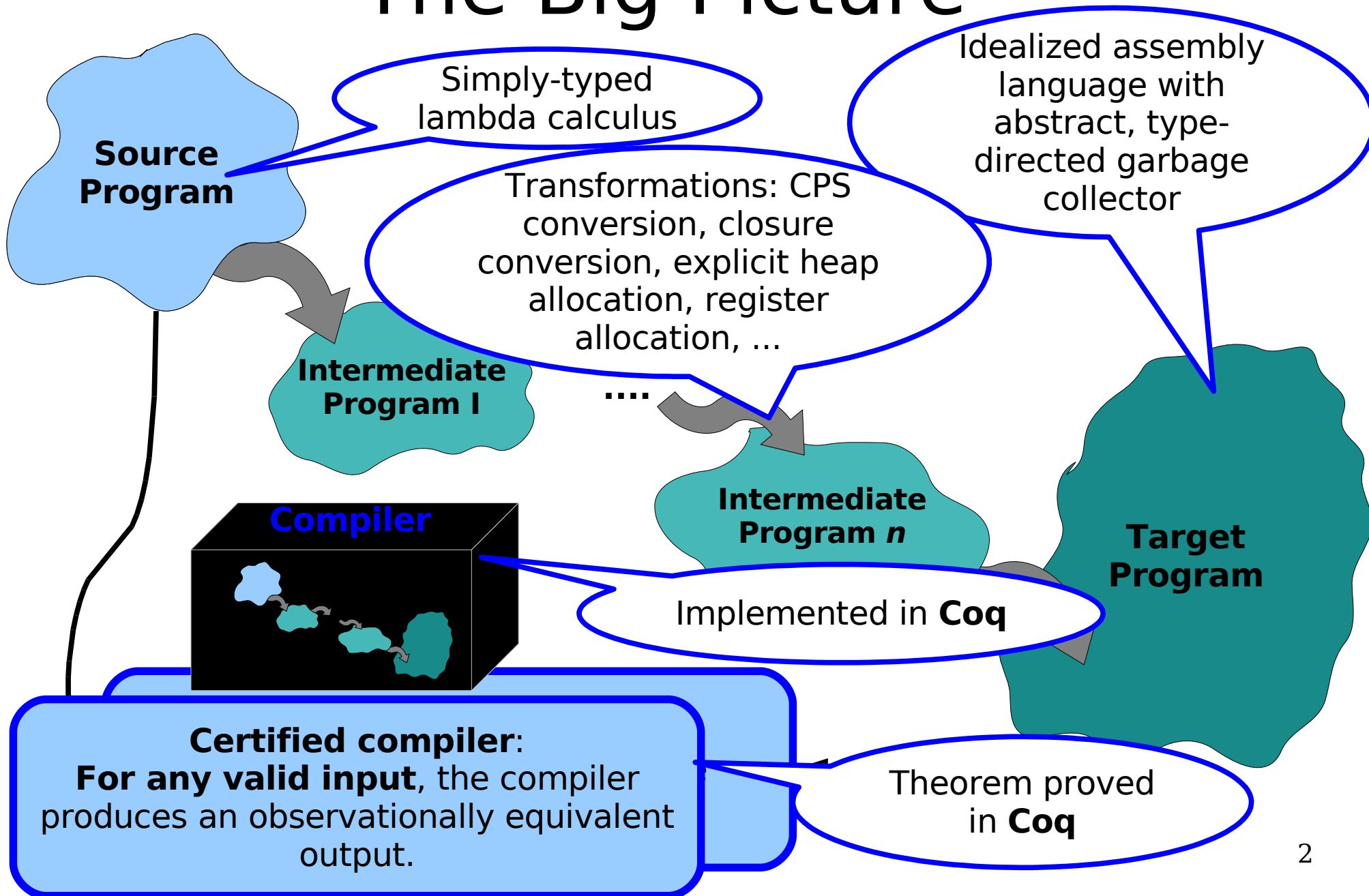


A Certified Type- Preserving Compiler from Lambda Calculus to Assembly Language

An experiment with variable binding, denotational semantics, and logical relations in Coq

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The Big Picture

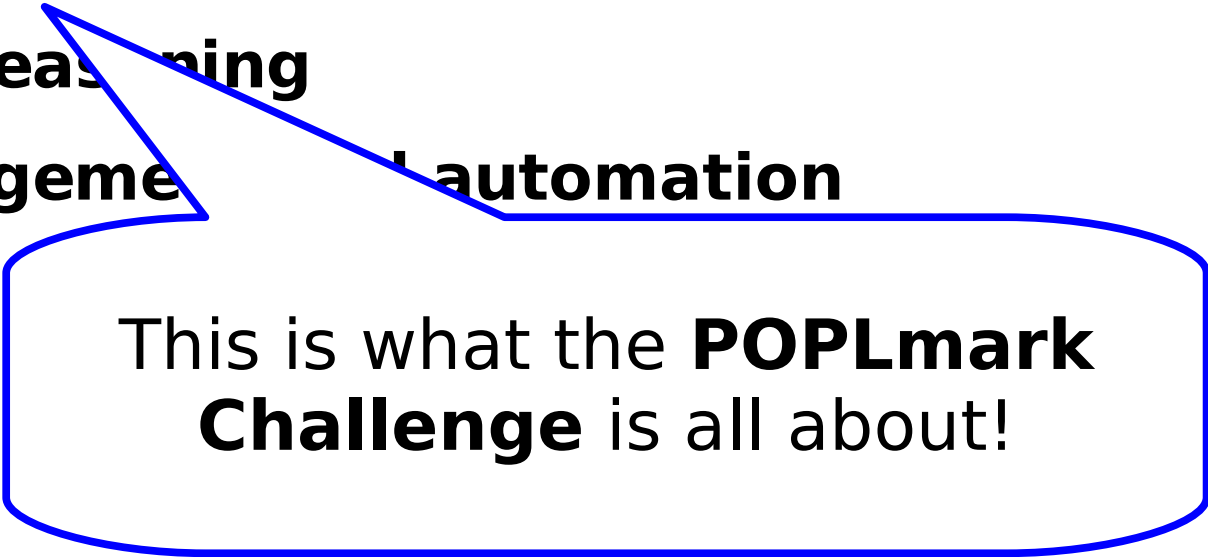


Type-Preserving Compilation

- Preserve **static type information** in some prefix of the compilation process.
- Taken all the way, you end up with **typed assembly language, proof-carrying code**, etc..
- More modestly, implement **nearly tag-free garbage collection**.
 - Replace tag bits, boxing, etc., with static tables mapping registers to types.
 - Used in the MLton SML compiler.

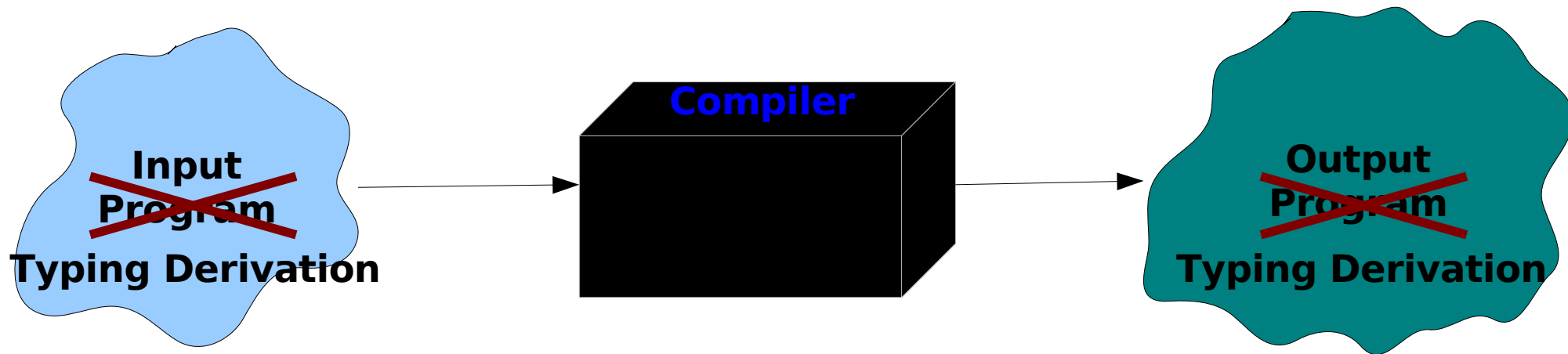
What's tricky?

- **Nested variable scopes**
- **Relational reasoning**
- **Proof management**
- **Automation**



This is what the **POPLmark Challenge** is all about!

Design Decision #1: Independently-Typed ASTs



Use **dependent types** to make the compiler **type-preserving by construction!**

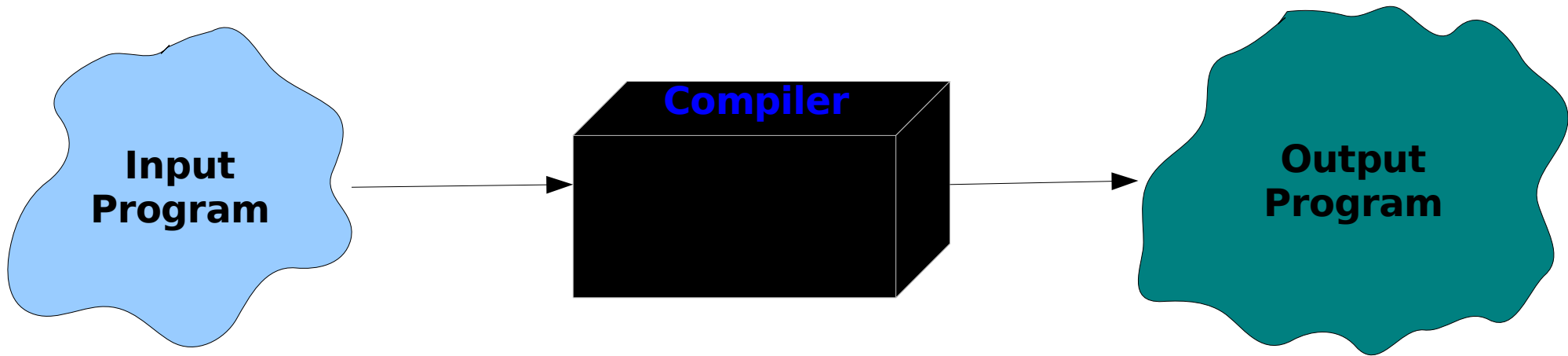
~~Type Preservation Theorem~~

~~If the input program has type T , then the output program has type $C(T)$.~~

Semantics Preservation Theorem.

If the input program has meaning M , then the output program has meaning $C(M)$.

Design Decision #2: Denotational Semantics



Denotational Semantics Version:

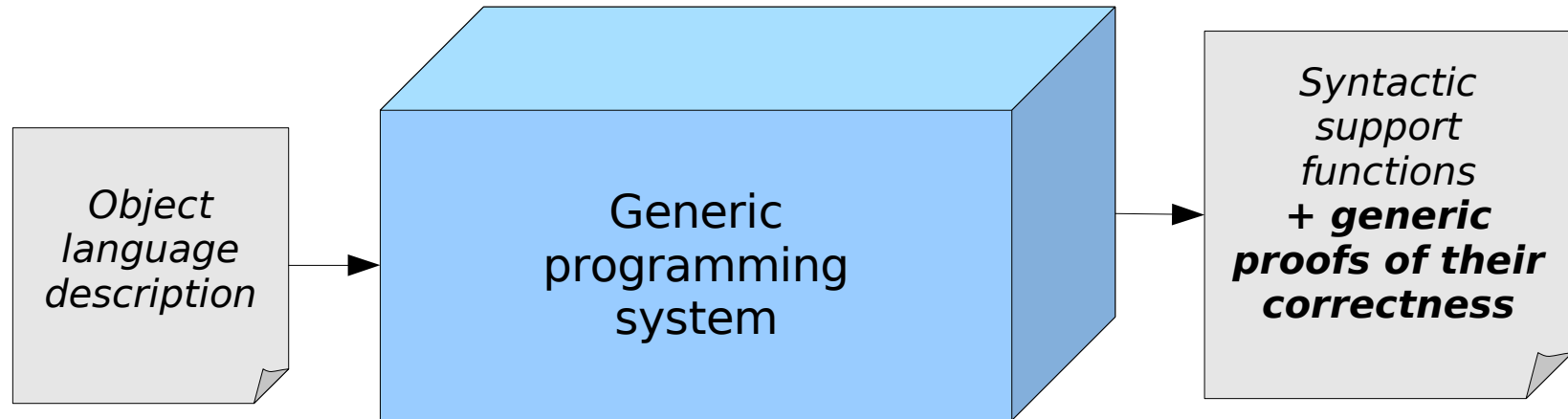
1. **Compile** the input program **to CIC**.
2. **Compile** the output program **to CIC**.
3. The two results must be **equal**.

Semantics Preservation Theorem.

If the input program has meaning M , then the output program has meaning $\mathbf{C}(M)$.

Secret Weapons

Programming with dependent types is hard!



Writing formal proofs is hard!

The trickiest bits deal with
functions that adjust
these are still in
language

The combination of **dependent types** and **denotational semantics** enables some very effective **decision procedures** to be coded in Coq's **Ltac language**.

“Put the rooster to work!”

Rest of the Talk...

- Summary of compilation
- Dependently-typed ASTs
- Denotational semantics in Coq
- Writing compiler passes
 - ...including generic programming of helper functions
- Proving semantics preservation

Source and Target Languages

Source language: **simply-typed lambda calculus**

$$\tau ::= \mathbf{N} \mid \tau \rightarrow \tau$$

$$e ::= n \mid x \mid e e \mid \lambda x : \tau, e$$

Target language: **idealized assembly language**

$$o ::= r \mid n \mid \mathbf{new}(R, R) \mid \mathbf{read}(r, n)$$

$$i ::= r := o; i \mid \mathbf{jump} \ r$$

$$p ::= (l, i)$$

Compiler Stages

$\lambda x, f\ x$

CPS conversion

$k_{\text{top}}(\lambda x, \lambda k, f\ x\ k)$

Closure conversion

let $F = \lambda e, \lambda x, \lambda k, e.1\ x\ k$ **in** $k_{\text{top}}(\langle F, [f] \rangle)$

Explicit heap allocation

let $F = \lambda e, \lambda x, \lambda k, e.1.1\ e.1.2\ x\ k$ **in**
let $r1 = [f]$ **in** **let** $r2 = [F, r1]$ **in** $k_{\text{top}}(r2)$

Flattening

F : $r4 := r1.1$; $r1 := r4.2$; $r4 := r4.1$; **jump** $r4$
 $main$: $r3 := r1.1$; $r1 := r1.2$;
 $r2 := \mathbf{new}\ [f]$; $r2 := \mathbf{new}\ [F, r2]$; **jump** $r3$

Correctness Proof

- Compiler and proof implemented entirely within **Coq 8.0**
- Axioms:
 - Functional extensionality:
$$\forall f, g, (\forall x, f(x) = g(x)) \Rightarrow f = g$$
 - Uniqueness of equality proofs:
$$\forall \tau, \forall x, y : \tau, \forall P1, P2 : x = y, P1 = P2$$
- The compiler is *almost* runnable as part of a proof.

Denotational Semantics of the Source Language

$$\begin{aligned}\llbracket \tau \rrbracket &: \text{types} \rightarrow \text{sets} \\ \llbracket \mathbf{N} \rrbracket &= \mathbb{N} \\ \llbracket \tau_1 \rightarrow \tau_2 \rrbracket &= \llbracket \tau_1 \rrbracket \rightarrow \llbracket \tau_2 \rrbracket\end{aligned}$$

$$\begin{aligned}\llbracket \Gamma \rrbracket &: \text{contexts} \rightarrow \text{sets} \\ \llbracket \cdot \rrbracket &= \mathbf{unit} \\ \llbracket \Gamma, x : \tau \rrbracket &= \llbracket \Gamma \rrbracket \times \llbracket \tau \rrbracket\end{aligned}$$

$$\begin{aligned}\llbracket e \rrbracket &: [\Gamma \vdash e : \tau] \rightarrow \llbracket \Gamma \rrbracket \rightarrow \llbracket \tau \rrbracket \\ \llbracket n \rrbracket \sigma &= \bar{n} \\ \llbracket x \rrbracket \sigma &= \sigma(x) \\ \llbracket e_1 \ e_2 \rrbracket \sigma &= \llbracket e_1 \rrbracket \sigma \ \llbracket e_2 \rrbracket \sigma \\ \llbracket \lambda x : \tau, e \rrbracket \sigma &= \lambda x : \llbracket \tau \rrbracket, \llbracket e \rrbracket(\sigma, x)\end{aligned}$$

For Types...

Inductive ty : **Set** :=
 | Nat : ty
 | Arrow : ty -> ty -> ty.

Fixpoint tyDenote (t : ty) : **Set** :=
 match t **with**
 | Nat => nat
 | Arrow t1 t2 => tyDenote t1 -> tyDenote t2
 end.

Representing Terms

Nominal syntax

Inductive term : Set :=

- | Const : nat -> term
- | Var : name -> term
- | Lam : name -> term -> term
- | App : term -> term -> term.

Representing Terms

De Bruijn syntax

Inductive term : Set :=

| Const : nat -> term

| Var : nat -> term

| Lam : term -> term

| App : term -> term -> term.

Representing Terms

Dependent de Bruijn syntax

Inductive term : nat -> Set :=

| Const : **forall** n, nat -> term n

| Var : **forall** n x, $x < n$ -> term n

| Lam : **forall** n, term (S n) -> term n

| App : **forall** n, term n -> term n -> term n.

Representing Terms

Dependent de Bruijn syntax with typing

Inductive term : list ty -> ty -> **Set** :=

| Const : **forall** G, nat -> term G Nat

| Var : **forall** G t, var G t -> term G t

| Lam : **forall** G dom ran, term (dom :: G) ran
-> term G (Arrow dom ran)

| App : **forall** G dom ran,
term G (Arrow dom ran)
-> term G dom
-> term G ran.

Term Denotations

```
Fixpoint termDenote ( $G$  : list ty) ( $t$  : ty) ( $e$  : term  $G$  t) {struct  $e$ }  
: subst tyDenote  $G$  -> tyDenote  $t$  :=  
match  $e$  in (term  $G$  t)  
    return (subst tyDenote  $G$  -> tyDenote  $t$ ) with  
  | Const _  $n$  => fun _ =>  $n$   
  | Var _ _  $x$  => fun  $s$  => varDenote  $x$   $s$   
  | Lam _ _  $e'$  => fun  $s$  =>  
    fun  $x$  => termDenote  $e'$  (SCons  $x$   $s$ )  
  | App _ _ _  $e1$   $e2$  => fun  $s$  =>  
    (termDenote  $e1$   $s$ ) (termDenote  $e2$   $s$ )  
end.
```

Definition of “Values” for Free

<u>Operational</u>	<u>Denotational</u>
--------------------	---------------------

n value

$\lambda x : \tau, e$ value

Syntactic
characterization used
throughout definitions
and proofs

$\llbracket \tau \rrbracket : \text{types} \rightarrow \text{sets}$

$\llbracket \mathbb{N} \rrbracket = \mathbb{N}$

$\llbracket \tau_1 \rightarrow \tau_2 \rrbracket = \llbracket \tau_1 \rrbracket \rightarrow \llbracket \tau_2 \rrbracket$

Inherit any “canonical forms” properties of the underlying Coq types.

“A natural number is either zero or a successor of another natural number.”

Caveat: We don't get the same kind of property for functions!

No Substitution Function!

Operational

$$n[x := e] = n$$

$$x[x := e] = e$$

$$y[x := e] = y$$

$$(e_1 e_2)[x := e] = e_1[x := e] e_2[x := e]$$

$$(\lambda x : \tau, e')[x := e] = \lambda x : \tau, e'$$

$$(\lambda y : \tau, e')[x := e] = \lambda y : \tau, e'[x := e]$$

Customized syntactic
substitution function written
for each object language

$$(\lambda x : \tau, e_1) e_2 \rightarrow e_1[x := e_2]$$

Reduction rules defined using
substitution

Denotational

$$\llbracket n \rrbracket \sigma = \bar{n}$$

$$\llbracket x \rrbracket \sigma = \sigma(x)$$

$$\llbracket e_1 e_2 \rrbracket \sigma = \llbracket e_1 \rrbracket \sigma \llbracket e_2 \rrbracket \sigma$$

$$\llbracket \lambda x : \tau, e \rrbracket \sigma = \lambda x : \llbracket \tau \rrbracket, \llbracket e \rrbracket (\sigma, x)$$

$$\begin{aligned} \llbracket (\lambda x : \mathbb{N}, x) 1 \rrbracket () &= \llbracket \lambda x : \mathbb{N}, x \rrbracket () \llbracket 1 \rrbracket () \\ &= (\lambda x : \mathbb{N}, x) 1 \\ &= 1 \end{aligned}$$


Coq's operational semantics
provides the substitution
operation for us!

Free Metatheorems

Operational

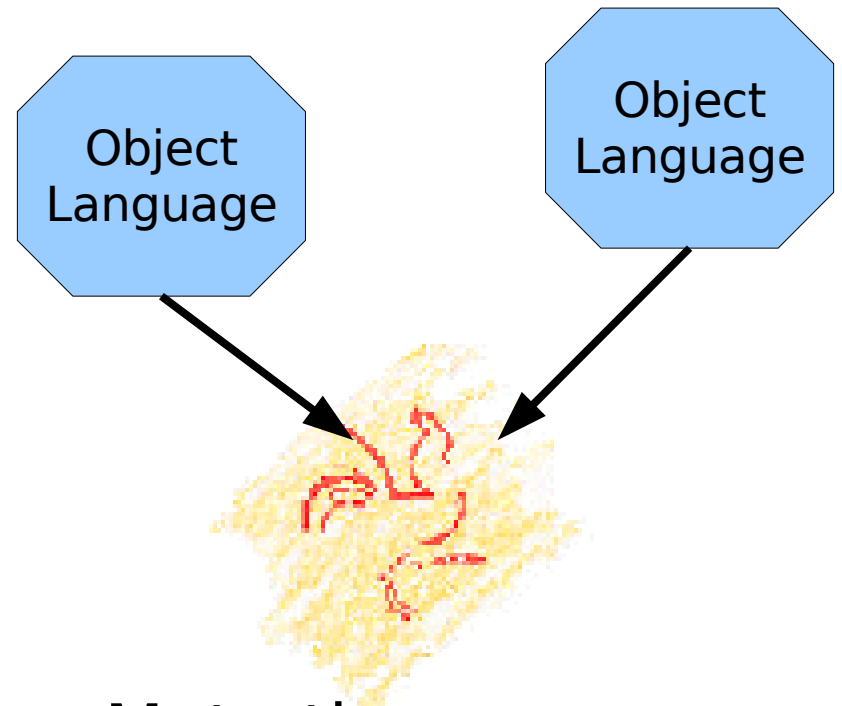
For each object language, give customized, syntactic proofs of properties like:

- Type safety – preservation
- Type safety – progress
- Confluence
- Strong normalization
- ...



The majority of programming language theory mechanization experiments only look at proving these sorts of theorems!

Denotational

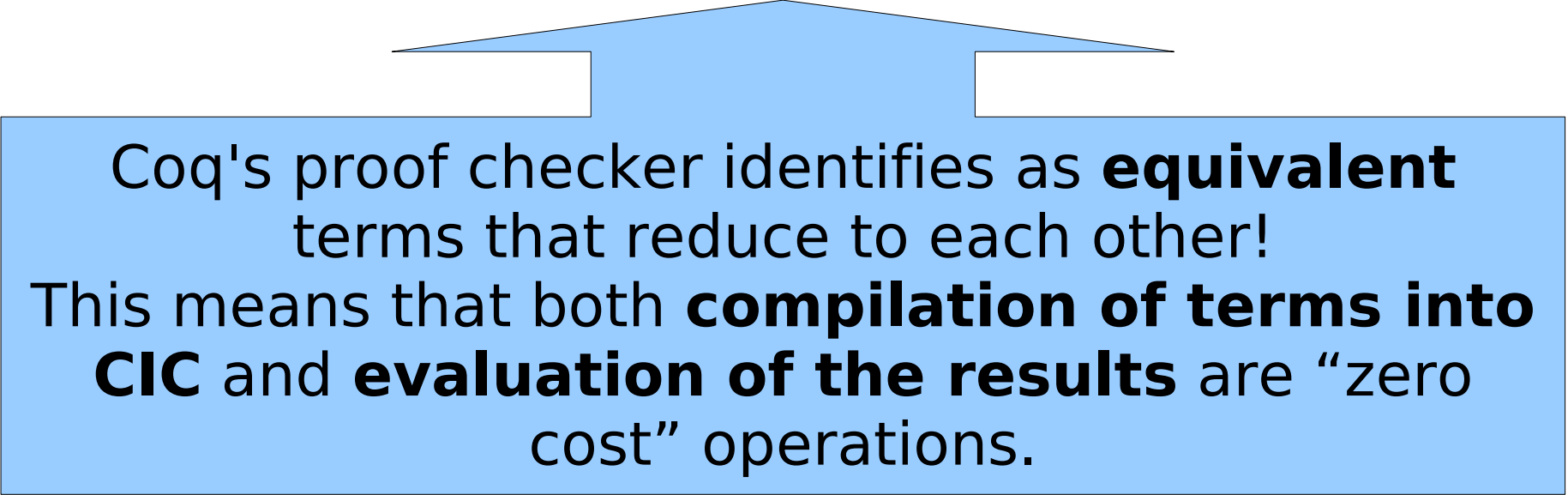


Meta-theorems
proved once and
for all about CIC

Free Theorems

Theorem 1 *For any n , $\llbracket (\lambda x : \mathbb{N}, x) n \rrbracket () = n$.*

Proof. By *reflexivity of equality*.



Coq's proof checker identifies as **equivalent** terms that reduce to each other!
This means that both **compilation of terms into CIC** and **evaluation of the results** are “zero cost” operations.

But Wait!

Doesn't that only work for languages that are:

- Strongly normalizing
- Purely functional
- Deterministic
- Single-threaded
- ...etc...

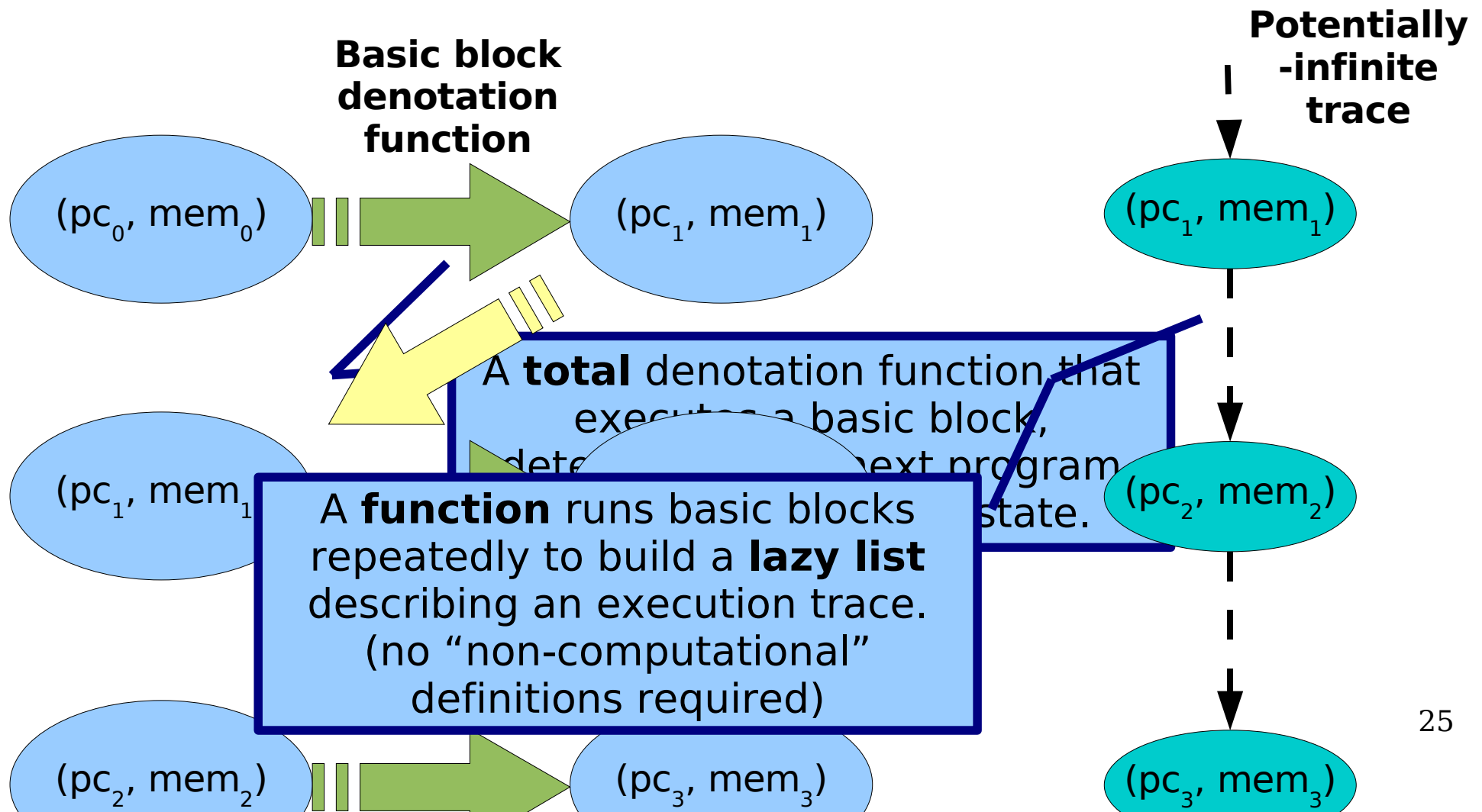
(In other words, a lot like Coq)

Monads to the Rescue!

- Summary rebuttal: Take a cue from Haskell.
- Use **object language agnostic** “embedded languages” to allow expression of “effectful” computations
- Keep using Coq's definitional equality to handle reasoning about pure sublanguages, and even some of the mechanics of impure pieces.

Non-Strongly-Normalizing Languages

For closed, first-order programs with basic block structure (e.g., structured assembly)



Co-inductive Traces

$$T ::= n \mid \perp \mid \star, T$$

Take one more step of computation.

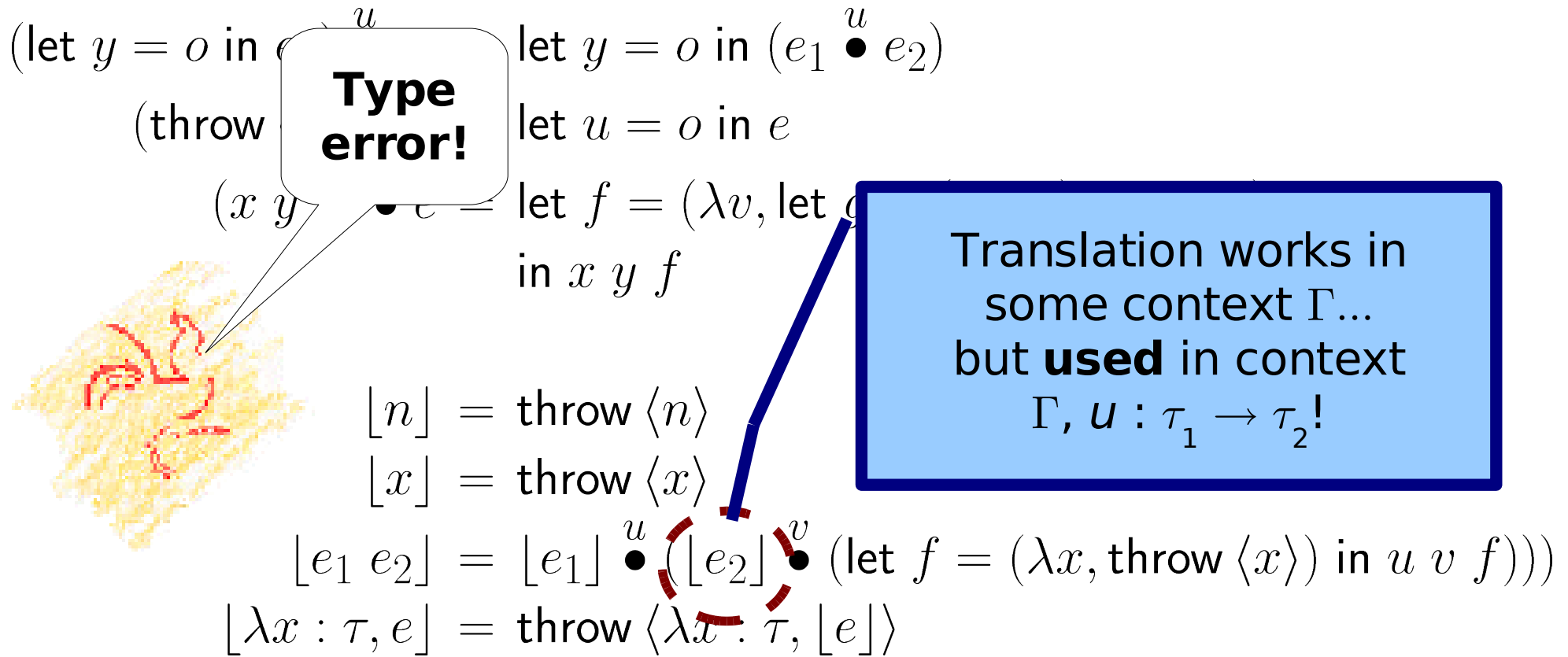
Run-time failure

By keeping only these summaries of program executions, we enable effective **equality reasoning**.

Example: **Garbage collection safety**

Equality of traces is a good way to characterize the appropriate effect on programs from rearranging the heap and root pointers to a new, isomorphic configuration.

Example Compilation Phase: CPS Transform



Recall that **terms are represented as typing derivations.**

We need a syntactic helper function equivalent to a **weakening lemma.**

Dependently-Typed Syntactic Helper Functions?

- Could just write this function from scratch for each new language.
 - Probably using tactic-based proof search
 - The brave (and patient) write the CIC term directly.
 - My recipe for writing generic substitution functions involves three auxiliary recursive functions!
- Much nicer to automate these details using generic programming!
 - Write each function once, **not** once per object language.

What Do We Need?

1. The helper function itself

$\text{weaken} : \mathbf{forall} (G : \text{list ty}) (t : \text{ty}), \text{term } G \ t$
 $\rightarrow \mathbf{forall} (t' : \text{ty}), \text{term } (t' :: G) \ t$

2. Lemmas about the function

For any term e , properly-typed substitution σ , and properly-typed value v :

$$\llbracket \text{weaken}(e) \rrbracket (\sigma, v) = \llbracket e \rrbracket \sigma$$

Can prove this generically for *any* **compositional** denotation function!

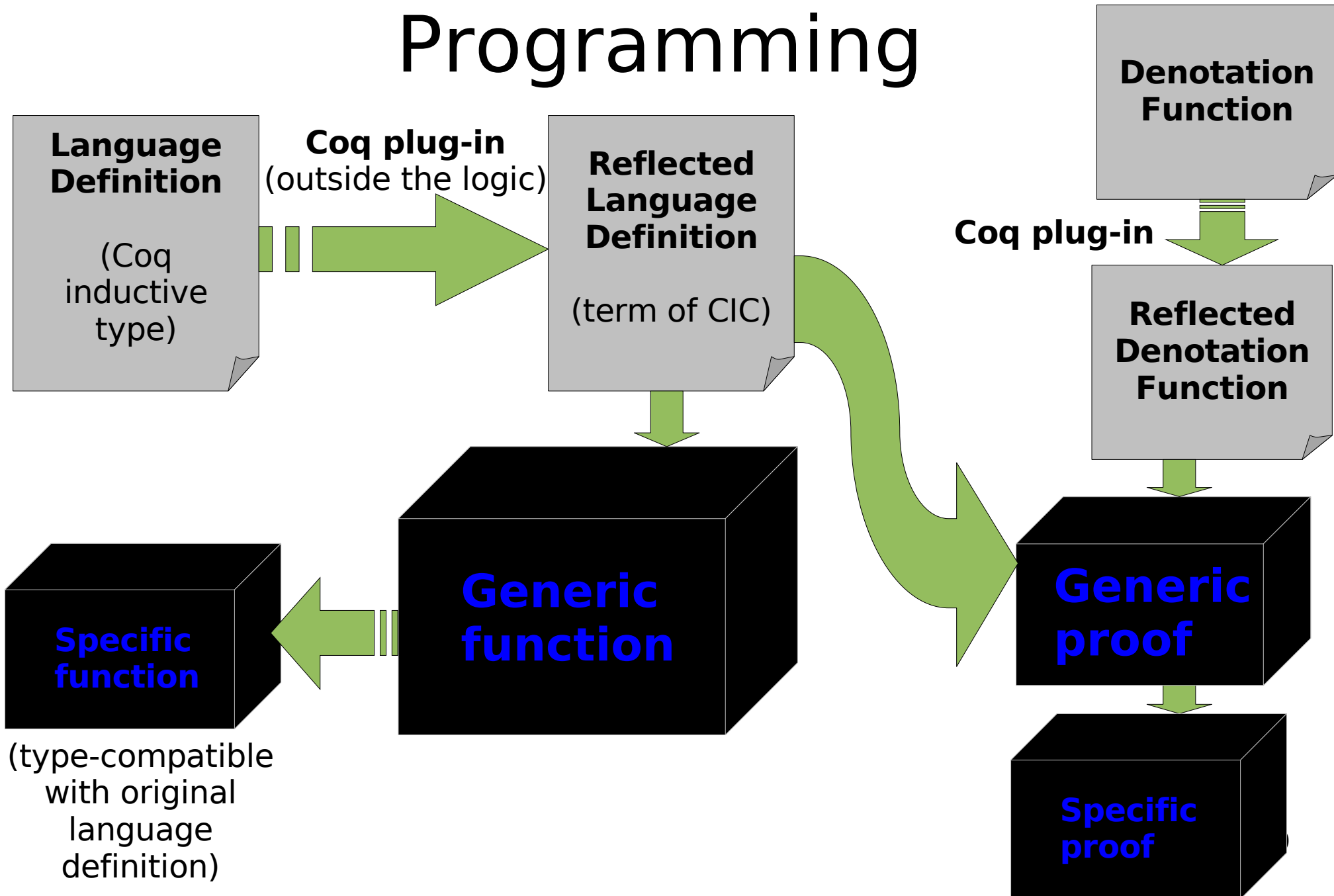
For example, for simply-typed lambda calculus, there must exist f_{var} , f_{app} , and f_{lam} such that:

$$\llbracket x \rrbracket \sigma = f_{\text{var}}(\sigma(x))$$

$$\llbracket e_1 \ e_2 \rrbracket \sigma = f_{\text{app}}(\llbracket e_1 \rrbracket \sigma, \llbracket e_2 \rrbracket \sigma)$$

$$\llbracket \lambda x : \tau, e \rrbracket \sigma = f_{\text{lam}}(\lambda x : \llbracket \tau \rrbracket, \llbracket e \rrbracket (\sigma, x))$$

Reflection-Based Generic Programming



What to Prove?

Overall correctness theorem: The compilation of a program of type **N** runs to the same result as the original program does.

What do we prove about individual phases?

Prove that input/output pairs are in an appropriate **logical relation**. E.g., for the CPS transform:

$$\begin{aligned}
 n_1 \simeq_{\mathbf{N}} n_2 &= n_1 = n_2 \\
 f_1 \simeq_{\tau_1 \rightarrow \tau_2} f_2 &= \forall x_1 : \llbracket \tau_1 \rrbracket^S, \forall x_2 : \llbracket \tau_1 \rrbracket^L, x_1 \simeq_{\tau_1} x_2 \\
 &\rightarrow \exists v : \llbracket \tau_2 \rrbracket^L, \forall k : \llbracket \tau_2 \rrbracket^L \rightarrow \mathbf{N}, \\
 &\quad f_1 x_1 \simeq_{\tau_2} v
 \end{aligned}$$

This function space contains many functions not representable in our object languages!

In the Trenches

$$\begin{array}{l}
 H_1 : \forall \sigma^S, \forall \sigma^L, \sigma^S \simeq_{\Gamma} \sigma^L \rightarrow \exists v : \llbracket \tau_1 \rightarrow \tau_2 \rrbracket^L, \\
 \quad \forall k : \llbracket \tau_1 \rightarrow \tau_2 \rrbracket^L \rightarrow \mathbb{N}, \llbracket [e_1] \rrbracket^L \sigma^L k = k v \wedge \llbracket [e_1] \rrbracket^S \sigma^S \simeq_{\tau_1 \rightarrow \tau_2} v \\
 H_2 : \forall \sigma^S, \forall \sigma^L, \sigma^S \simeq_{\Gamma} \sigma^L \rightarrow \exists v : \llbracket \tau_1 \rrbracket^L, \\
 \quad \forall k : \llbracket \tau_1 \rrbracket^L \rightarrow \mathbb{N}, \llbracket [e_2] \rrbracket^L \sigma^L k = k v \wedge \llbracket [e_2] \rrbracket^S \sigma^S \simeq_{\tau_1} v \\
 \hline
 \quad \forall \sigma^S, \forall \sigma^L, \sigma^S \simeq_{\Gamma} \sigma^L \rightarrow \exists v : \llbracket \tau_2 \rrbracket^L, \\
 \quad \forall k : \llbracket \tau_2 \rrbracket^L \rightarrow \mathbb{N}, \llbracket [e_1 \ e_2] \rrbracket^L \sigma^L k = k v \wedge \llbracket [e_1 \ e_2] \rrbracket^S \sigma^S \simeq_{\tau_2} v
 \end{array}$$

Easy first step: Use introduction rules for forall's and implications at the start of the goal.

In the Trenches

$$\begin{array}{l}
 H_1 : \forall \sigma^S, \forall \sigma^L, \sigma^S \simeq_{\Gamma} \sigma^L \rightarrow \exists v : \llbracket \tau_1 \rightarrow \tau_2 \rrbracket^L, \\
 \quad \forall k : \llbracket \tau_1 \rightarrow \tau_2 \rrbracket^L \rightarrow \mathbb{N}, \llbracket [e_1] \rrbracket^L \sigma^L k = k v \wedge \llbracket [e_1] \rrbracket^S \sigma^S \simeq_{\tau_1 \rightarrow \tau_2} v \\
 H_2 : \forall \sigma^S, \forall \sigma^L, \sigma^S \simeq_{\Gamma} \sigma^L \rightarrow \exists v : \llbracket \tau_1 \rrbracket^L \rightarrow \mathbb{N}, \\
 \quad \forall k : \llbracket \tau_1 \rrbracket^L \rightarrow \mathbb{N} \\
 \sigma^S : \dots \\
 \sigma^L : \dots \\
 H_3 : \sigma^S \simeq_{\Gamma} \sigma^L \\
 \quad \exists v : \llbracket \tau_2 \rrbracket^L, \\
 \quad \forall k : \llbracket \tau_2 \rrbracket^L \rightarrow \mathbb{N}, \llbracket [e_1 \ e_2] \rrbracket^L \sigma^L k = k v \wedge \llbracket [e_1 \ e_2] \rrbracket^S \sigma^S \simeq_{\tau_2} v
 \end{array}$$

Key observation: The quantified variables have **very specific dependent types**.

We can use **greedy quantifier instantiation!**

Now we're blocked at the tricky point for automated provers: proving existential facts and applying universal facts.

In the Trenches

$$\begin{array}{l}
 H_1 : \forall \sigma^S, \forall \sigma^L, \sigma^S \simeq_{\Gamma} \sigma^L \rightarrow \exists v : \llbracket \tau_1 \rightarrow \tau_2 \rrbracket^L, \\
 \quad \forall k : \llbracket \tau_1 \rightarrow \tau_2 \rrbracket^L \rightarrow \mathbb{N}, \llbracket [e_1] \rrbracket^L \sigma^L k = k v \wedge \llbracket [e_1] \rrbracket^S \sigma^S \simeq_{\tau_1 \rightarrow \tau_2} v \\
 H_2 : \forall \sigma^S, \forall \sigma^L, \sigma^S \simeq_{\Gamma} \sigma^L \rightarrow \exists v : \llbracket \tau_1 \rrbracket^L, \\
 \quad \forall k : \llbracket \tau_1 \rrbracket^L \rightarrow \mathbb{N}, \llbracket [e_2] \rrbracket^L \sigma^L k = k v \wedge \llbracket [e_2] \rrbracket^S \sigma^S \simeq_{\tau_1} v \\
 \sigma^S : \dots \\
 \sigma^L : \dots \\
 H_3 : \sigma^S \simeq_{\Gamma} \sigma^L
 \end{array}$$

$$\begin{array}{l}
 \exists v : \llbracket \tau_2 \rrbracket^L, \\
 \forall k : \llbracket \tau_2 \rrbracket^L \rightarrow \mathbb{N}, \llbracket [e_1 \ e_2] \rrbracket^L \sigma^L k = k v \wedge \llbracket [e_1 \ e_2] \rrbracket^S \sigma^S \simeq_{\tau_2} v
 \end{array}$$

In the Trenches

$$\begin{array}{l}
 H_1 : \exists v : \llbracket \tau_1 \rightarrow \tau_2 \rrbracket^L, \\
 \quad \forall k : \llbracket \tau_1 \rightarrow \tau_2 \rrbracket^L \rightarrow \mathbb{N}, \llbracket [e_1] \rrbracket^L \sigma^L k = k v \wedge \llbracket e_1 \rrbracket^S \sigma^S \simeq_{\tau_1 \rightarrow \tau_2} v \\
 H_2 : \forall \sigma^S, \forall \sigma^L, \sigma^S \simeq_{\Gamma} \sigma^L \rightarrow \exists v : \llbracket \tau_1 \rrbracket^L, \\
 \quad \forall k : \llbracket \tau_1 \rrbracket^L \rightarrow \mathbb{N}, \llbracket [e_2] \rrbracket^L \sigma^L k = k v \wedge \llbracket e_2 \rrbracket^S \sigma^S \simeq_{\tau_1} v \\
 \sigma^S : \dots \\
 \sigma^L : \dots \\
 H_3 : \sigma^S \simeq_{\Gamma} \sigma^L \\
 \hline
 \quad \exists v : \llbracket \tau_2 \rrbracket^L, \\
 \quad \forall k : \llbracket \tau_2 \rrbracket^L \rightarrow \mathbb{N}, \llbracket [e_1 \ e_2] \rrbracket^L \sigma^L k = k v \wedge \llbracket e_1 \ e_2 \rrbracket^S \sigma^S \simeq_{\tau_2} v
 \end{array}$$

Existential hypotheses are easy to eliminate.

In the Trenches

$$\begin{array}{l}
 v_1 : \llbracket \tau_1 \rightarrow \tau_2 \rrbracket^L \\
 H_1 : \forall k : \llbracket \tau_1 \rightarrow \tau_2 \rrbracket^L \rightarrow \mathbb{N}, \llbracket \llbracket e_1 \rrbracket \rrbracket^L \sigma^L k = k v_1 \wedge \llbracket e_1 \rrbracket^S \sigma^S \simeq_{\tau_1 \rightarrow \tau_2} v_1 \\
 H_2 : \forall \sigma^S, \forall \sigma^L, \sigma^S \simeq_{\Gamma} \sigma^L \rightarrow \exists v : \llbracket \tau_1 \rrbracket^L, \\
 \quad \forall k : \llbracket \tau_1 \rrbracket^L \rightarrow \mathbb{N}, \llbracket \llbracket e_2 \rrbracket \rrbracket^L \sigma^L k = k v \wedge \llbracket e_2 \rrbracket^S \sigma^S \simeq_{\tau_1} v \\
 \sigma^S : \dots \\
 \sigma^L : \dots \\
 H_3 : \sigma^S \simeq_{\Gamma} \sigma^L \\
 \hline
 \exists v : \llbracket \tau_2 \rrbracket^L, \\
 \forall k : \llbracket \tau_2 \rrbracket^L \rightarrow \mathbb{N}, \llbracket \llbracket e_1 \ e_2 \rrbracket \rrbracket^L \sigma^L k = k v \wedge \llbracket e_1 \ e_2 \rrbracket^S \sigma^S \simeq_{\tau_2} v
 \end{array}$$

We can't make further progress with this hypothesis, since no term of the type given for k exists in the proof state.

In the Trenches

$$\begin{array}{l}
 v_1 : \llbracket \tau_1 \rightarrow \tau_2 \rrbracket^L \\
 H_1 : \forall k : \llbracket \tau_1 \rightarrow \tau_2 \rrbracket^L \rightarrow \mathbb{N}, \llbracket \llbracket e_1 \rrbracket \rrbracket^L \sigma^L k = k v_1 \wedge \llbracket e_1 \rrbracket^S \sigma^S \simeq_{\tau_1 \rightarrow \tau_2} v_1 \\
 v_2 : \llbracket \tau_1 \rrbracket^L \\
 H_2 : \forall k : \llbracket \tau_1 \rrbracket^L \rightarrow \mathbb{N}, \llbracket \llbracket e_2 \rrbracket \rrbracket^L \sigma^L k = k v_2 \wedge \llbracket e_2 \rrbracket^S \sigma^S \simeq_{\tau_1} v_2 \\
 \sigma^S : \dots \\
 \sigma^L : \dots \\
 H_3 : \sigma^S \simeq_{\Gamma} \sigma^L
 \end{array}$$

$$\begin{array}{l}
 \exists v : \llbracket \tau_2 \rrbracket^L, \\
 \forall k : \llbracket \tau_2 \rrbracket^L \rightarrow \mathbb{N}, \llbracket \llbracket e_1 \ e_2 \rrbracket \rrbracket^L \sigma^L k = k v \wedge \llbracket e_1 \ e_2 \rrbracket^S \sigma^S \simeq_{\tau_2} v
 \end{array}$$

We can simplify the conclusion by applying rewrite rules (like those we generated automatically) until no more apply.

In the Trenches

$$\begin{array}{l}
 v_1 : \llbracket \tau_1 \rightarrow \tau_2 \rrbracket^L \\
 H_1 : \forall k : \llbracket \tau_1 \rightarrow \tau_2 \rrbracket^L \rightarrow \mathbb{N}, \llbracket \llbracket e_1 \rrbracket \rrbracket^L \sigma^L k = k v_1 \wedge \llbracket e_1 \rrbracket^S \sigma^S \simeq_{\tau_1 \rightarrow \tau_2} v_1 \\
 v_2 : \llbracket \tau_1 \rrbracket^L \\
 H_2 : \forall k : \llbracket \tau_1 \rrbracket^L \rightarrow \mathbb{N}, \llbracket \llbracket e_2 \rrbracket \rrbracket^L \sigma^L k = k v_2 \wedge \llbracket e_2 \rrbracket^S \sigma^S \simeq_{\tau_1} v_2 \\
 \sigma^S : \dots \\
 \sigma^L : \dots \\
 H_3 : \sigma^S \simeq_{\Gamma} \sigma^L
 \end{array}$$

$$\begin{array}{l}
 \exists v : \llbracket \tau_2 \rrbracket^L, \\
 \forall k : \llbracket \tau_2 \rrbracket^L \rightarrow \mathbb{N}, \llbracket \llbracket e_1 \rrbracket \rrbracket^L \sigma^L (\lambda x : \llbracket \tau_1 \rightarrow \tau_2 \rrbracket^L, \dots) \equiv \dots \wedge \dots
 \end{array}$$

Now the conclusion has a subterm with the right type to instantiate a hypothesis!

In the Trenches

$$\begin{array}{l}
 v_1 : \llbracket \tau_1 \rightarrow \tau_2 \rrbracket^L \\
 H_1 : \llbracket \llbracket e_1 \rrbracket \rrbracket^L \sigma^L (\lambda x : \llbracket \tau_1 \rightarrow \tau_2 \rrbracket^L, \dots) = (\lambda x : \llbracket \tau_1 \rightarrow \tau_2 \rrbracket^L, \dots) v_1 \wedge \dots \\
 v_2 : \llbracket \tau_1 \rrbracket^L \\
 H_2 : \forall k : \llbracket \tau_1 \rrbracket^L \rightarrow \mathbb{N}, \llbracket \llbracket e_2 \rrbracket \rrbracket^L \sigma^L k = k \rightarrow v_2 \wedge \llbracket e_2 \rrbracket^S \sigma^S \simeq_{\tau_1} v_2 \\
 \sigma^S : \dots \\
 \sigma^L : \dots \\
 H_3 : \sigma^S \simeq_{\Gamma} \sigma^L
 \end{array}$$

$$\begin{array}{l}
 \exists v : \llbracket \tau_2 \rrbracket^L, \\
 \forall k : \llbracket \tau_2 \rrbracket^L \rightarrow \mathbb{N}, \llbracket \llbracket e_1 \rrbracket \rrbracket^L \sigma^L (\lambda x : \llbracket \tau_1 \rightarrow \tau_2 \rrbracket^L, \dots) \Rightarrow \dots \wedge \dots
 \end{array}$$

We can use H_1 to rewrite the goal.

In the Trenches

$$\begin{aligned}
 v_1 &: \llbracket \tau_1 \rightarrow \tau_2 \rrbracket^L \\
 H_1 &: \llbracket [e_1] \rrbracket^L \sigma^L (\lambda x : \llbracket \tau_1 \rightarrow \tau_2 \rrbracket^L, \dots) = (\lambda x : \llbracket \tau_1 \rightarrow \tau_2 \rrbracket^L, \dots) v_1 \wedge \dots \\
 v_2 &: \llbracket \tau_1 \rrbracket^L \\
 H_2 &: \forall k : \llbracket \tau_1 \rrbracket^L \rightarrow \mathbb{N}, \llbracket [e_2] \rrbracket^L \sigma^L k = k v_2 \wedge \llbracket [e_2] \rrbracket^S \sigma^S \simeq_{\tau_1} v_2 \\
 \sigma^S &: \dots \\
 \sigma^L &: \dots \\
 H_3 &: \sigma^S \simeq_{\Gamma} \sigma^L
 \end{aligned}$$

$$\begin{aligned}
 &\exists v : \llbracket \tau_2 \rrbracket^L, \\
 &\forall k : \llbracket \tau_2 \rrbracket^L \rightarrow \mathbb{N}, (\lambda x : \llbracket \tau_1 \rightarrow \tau_2 \rrbracket^L, \dots) v_1 = \dots \wedge \dots
 \end{aligned}$$

And That's That!

- This strategy does almost all of the proving for the CPS transformation correctness proof!
 - About 20 lines of proof script total.
- Basic approach:
 - Figure out the right syntactic rewrite lemmas, prove them, and add them as hints.
 - State the induction principle to use.
 - Call a generic tactic from a library.

A Recipe for Certified Compilers

1. Define object languages with **dependently-typed ASTs**.
2. Give object languages **denotational semantics**.
3. Use **generic programming** to build basic support functions and lemmas.
4. Write compiler phases as dependently-typed Coq functions.
5. Express phase correctness with **logical relations**.
6. Prove correctness theorems using a generic decision procedure relying heavily on **greedy quantifier instantiation**.

Design Decisions

- Why dependently-typed ASTs?
 - Avoid well-formedness side conditions
 - Easy to construct denotational semantics defined only over well-typed terms
 - Makes greedy quantifier instantiation realistic
- Why denotational semantics?
 - Concise to define
 - Known to work well with code transformation
 - Many reasoning steps come for free via Coq's definitional equality

Conclusion

- Yet another bag of suggestions on how to formalize programming languages and their metatheories and tools!
- Would be interesting to see other approaches to formalizing this kind of compilation.

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